

An autonomous data gathering scheme adaptive to sensing requirements for industrial environment monitoring

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Agenda

- Research background
 - Monitoring of shaft furnace in steel plant
- An autonomous data gathering scheme
 - Adaptive sensing task engagement using **response threshold model**
 - Energy efficient transmission and sleep scheduling using **pulse-coupled oscillator model**
- Simulation results and demonstration
- Conclusion and future work

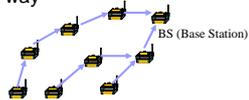
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Wireless sensor networks (1)

- A data gathering scheme for wireless sensor networks must be:
 - Energy-efficient
 - A sensor node is typically powered by a battery that cannot be easily replaced
 - Fully-distributed, self-organizing
 - A large number of sensor nodes are often deployed and distributed in an uncontrolled way



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Wireless sensor networks (2)

- In periodical data gathering, sleep scheduling is good to save energy consumption
- In some classes of applications,
 - A sensor node needs to change its sensing interval to monitor the region more frequently when it detects unusual conditions and phenomena.
 - The number of sensor nodes which monitor and report the phenomena should be regulated in accordance with its criticality and importance.

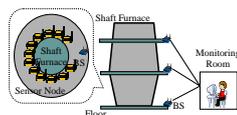
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Shaft furnace in steel plant

- Deployment of temperature and CO gas sensors
 - Temperature changes slowly or stays long period
 - CO gas may suddenly appear, move fast, and dissipate
- Three intervals of monitoring are required
 - Monitoring temperature and CO gas in stable conditions
 - Monitoring temperature more frequently when changes are detected
 - Monitoring CO gas more frequently than temperature when CO gas is detected



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Research target

- Proposal of a data gathering scheme adaptive to sensing requirements
- To accomplish self-organizing control:
 - Adaptive sensing task engagement
 - **Response threshold model**
 - Energy efficient transmission and sleep scheduling
 - **Pulse-coupled oscillator model**

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Sensing state

- All sensor nodes have k_{max} sensing devices
 - Ex) temperature, CO gas
- Sensor node i has two sensing state for each sensor k
 - Normal state**
 - Monitoring at a normal interval of T sec.
 - Frequent state**
 - Monitoring at a new interval of T_k sec. ($T_k < T$)
 - To relay sensor data from sensor node i to a BS (base station), sensor nodes on the path from sensor node i to the BS also change their operation interval to T_k sec.

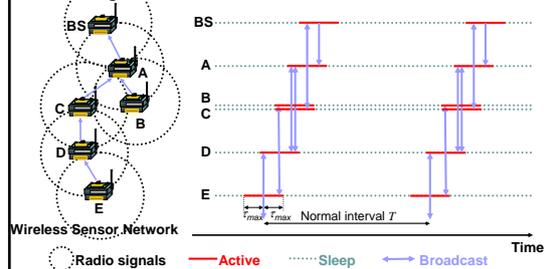
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Basic behavior in normal state

- Timing of broadcast emission



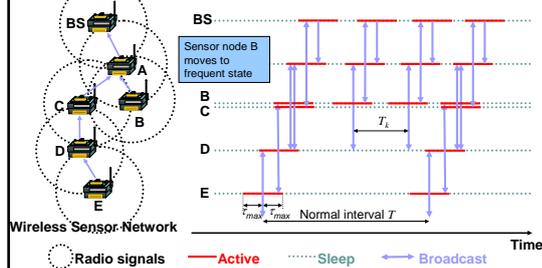
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Basic behavior in frequent state

- Timing of broadcast emission



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Decision of sensing state (1)

- To decide a sensing state in self-organizing manner, we use **response threshold model**
 - Mathematical model of division of labor and task allocation in social insects
- Demand of sensing target k at sensor node i

$$\frac{ds_{i,k}}{dt} = \delta_{i,k}(t) - \alpha \frac{m_{i,k}(t)}{n_{i,k}(t)}$$

$m_{i,k}$: the number of neighbor nodes in frequent state

$n_{i,k}$: total number of neighbor nodes

$\delta_{i,k}$: rate of temperature change / CO gas value itself

If the number of workers is insufficient, the demand increases

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Decision of sensing state (2)

- Probability of state transition

$$P(\text{normal state} \rightarrow \text{frequent state}) = \frac{s_{i,k}^2(t)}{s_{i,k}^2(t) + \theta_{i,k}^2(t)}$$

$$P(\text{frequent state} \rightarrow \text{normal state}) = p_{i,k}(t)$$

- Adjustment of threshold θ_i

$$\frac{d\theta_i}{dt} = \begin{cases} -\xi & \text{if } i \text{ performs frequent sensing} \\ +\varphi & \text{otherwise} \end{cases}$$

This threshold adjustment makes specialists having a small threshold and keep sensing the target frequently.

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Maintenance of broadcast timing (1)

- To autonomously generate and maintain timing of message propagation, we use **pulse-coupled oscillator model**
 - Mathematical model of synchronization observed in a group of flashing fireflies

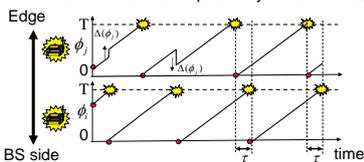
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Maintenance of broadcast timing (2)

- Sensor node behavior
 - Sensor node has phase $\phi \in [0, T]$
 - When the phase reaches T , the sensor node i broadcasts a message and the phase jumps back to 0
 - Neighboring sensor node closer to edge of WSN are stimulated and advance their phase by an amount $\Delta(\phi)$



By exchanging messages and using appropriate Δ , message propagation keeping a fixed phase difference τ is accomplished regardless of initial condition [2]

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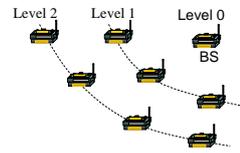
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Control parameters

- Sensor node i has:

- Phase ϕ_i
- Offset τ_i
- Level value l_i
 - Number of hops from BS
- Sensing state vector X_i
- Relay flag vector F_i
 - Used to notify downstream nodes of the existence of upstream nodes in frequent state
- Parameters of response threshold model
- Sensor data D_i



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Sensor node behavior

- Sensor node behaves in accordance with its phase and relay flag vector
- Sensor node periodically acts as follow:
 - Wake up
 - Receive broadcast messages from upstream node
 - Receive broadcast messages from same-hop node
 - Monitor and broadcast a message
 - Receive broadcast messages from downstream node
 - Sleep
- Details are in the paper

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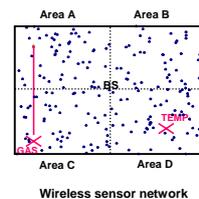
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Simulation experiments

- Simulation settings

- 200 nodes are randomly distributed in $100 \times 100 \text{ m}^2$ region
- Range of radio signals is fixed at 20 m
- Energy model is based on MICAz
- Data gathering intervals
 - Normal state: 160 sec.
 - Temperature frequently state: 40 sec.
 - CO gas frequently state: 10 sec.



- Simulation scenario

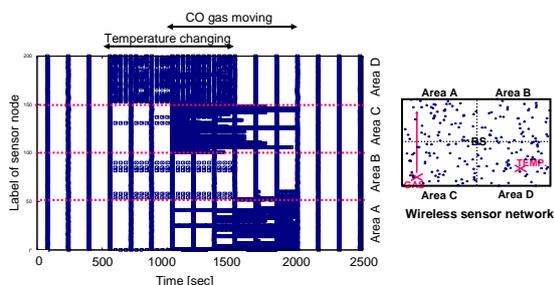
- From 500 to 1500 seconds, temperature increases in Area D
- From 1000 to 2000 seconds, CO gas leaks in Area C and moves to Area A at 0.08 m/sec .

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Timing of message emissions



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Energy consumption / duty cycle

- Adaptive intervals at 10/40/160 sec. (Proposal)

- Total energy consumption: 57.6 mJ/node
- Duty cycle: 0.03/node

- Fixed intervals at 10 sec.

- Total energy consumption: 632 mJ/node
- Duty cycle: 0.2 /node

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Demonstration

- Simulator
 - Red node: active
 - Gray node: sleeping
 - Pink region: temperature is changing
 - Blue region: CO gas is exist
- Data gathering intervals
 - Normal state: 32 sec.
 - Temperature frequently state: 8 sec.
 - CO gas frequently state: 4 sec.



- Simulation scenario
 - Temperature increases and stays in an area
 - CO gas leaks, moves, and disappears

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Conclusion and future work

- Proposal of a data gathering scheme for industrial environment monitoring
 - Adaptive sensing task engagement using response threshold model
 - Energy efficient transmission and sleep scheduling using pulse-coupled oscillator model
- Preliminary simulation experiments
 - Autonomous and energy-efficient data gathering
- Future work
 - In-depth evaluation of the sensing adaptability
 - Implementation of our scheme

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Thank you